

ミニマックス最適かつベイズ最適な最適腕識別

Minimax and Bayes Optimal Best-Arm Identification
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Masahiro Kato
Mizuho-DL Financial Technology



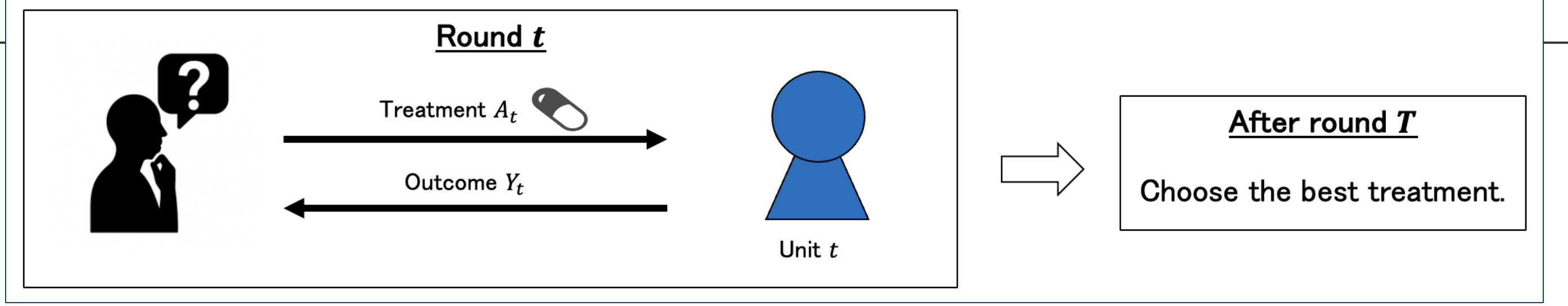
Best-Arm Identification (BAI) with a Fixed Budget

Setup

- **K Arms** indexed by $1, 2, \dots, K$. Also referred to as **treatment arms** or **arms**.
- **Potential outcome**. $Y_a \in \mathbb{R}$.
- **Distribution**. Y_a follows a distribution P_{μ} , where $\mu = (\mu_a)_{a \in [K]} \in \mathbb{R}^K$.
 - The mean of Y_a is μ_a (and only the mean can take different values).
 - For simplicity, let P_{μ} be a Gaussian distribution with variance σ_a^2 .
- **Goal**. Find the following **best arm** $a_{\mu}^* := \arg \max_{a \in \{1, 2, \dots, K\}} \mu_a$ efficiently:

Procedure

- **Adaptive experimental design with T rounds**
 1. **Allocation phase**: in each round $t = 1, 2, \dots, T$:
 - Draw arm $A_t \in [K] := \{1, 2, \dots, K\}$ using $\{(A_s, Y_s)\}_{s=1}^{t-1}$.
 - Observe the outcome $Y_t = \sum_{a \in [K]} 1[A_t = a] Y_{a,t}$.
 2. **Decision-making phase**: at the end of the experiment:
 - Obtain an estimator $\hat{a}_T$ of the the best arm using $\{(X_t, A_t, Y_t)\}_{t=1}^T$.



Regret

- **Expected simple regret**: $\text{Regret}_{\mu} := \mathbb{E}_{\mu} [Y_{a_{\mu}^*} - Y_{\hat{a}_T}]$.
- Our goal is to minimize the expected simple regret.

Evaluation framework

- **Minimax analysis**.
 - Evaluate the regret for the worst-case μ .
 - We evaluate $\sup_{\mu \in \mathbb{R}^K} \text{Regret}_{\mu}$.
- **Bayes analysis**.
 - A prior Π is given.
 - Evaluate the regret by summing them weighted by the prior.
 - We evaluate $\int_{\mathbb{R}^K} \text{Regret}_{\mu} d\Pi(\mu)$.

Two-Stage (TS)-Empirical-Best-Arm (EBA) Strategy

- **Two-Stage-Empirical-Best-Arm (TS-EBA) Strategy $\delta^{\text{TS-EBA}}$** .

1. Allocation phase

Split T into the first rT rounds and the second $(1-r)T$ rounds.

① First stage:

- Allocate each arm with equivalent ratio $\frac{rT}{K}$.
- We select candidates of the best arms as $\hat{\mathcal{S}} \subseteq [K]$.
- Obtain an estimator $\hat{\sigma}_{a,rT}^2$ of the variance σ_a^2 . (sample variance).

② Second stage (we do not allocate arm $a \notin \hat{\mathcal{S}}$ from this stage):

- If $|\hat{\mathcal{S}}| = 1$, return arm $a \in \hat{\mathcal{S}}$ as an estimate of the best arm.
- If $|\hat{\mathcal{S}}| = 2$, allocate arm $a \in \hat{\mathcal{S}}$ with probability $w_{a,t} := \frac{\hat{\sigma}_{a,rT}}{\hat{\sigma}_{1,rT} + \hat{\sigma}_{2,rT}}$.
- If $|\hat{\mathcal{S}}| \geq 3$, allocate arm $a \in \hat{\mathcal{S}}$ with probability $w_{a,t} := \frac{\hat{\sigma}_{a,rT}}{\sum_{b \in \hat{\mathcal{S}}} \hat{\sigma}_{b,rT}^2}$.

2. Decision-making phase:

- Return $\hat{a}_T = \arg \max_{a \in [K]} \hat{\mu}_{a,T}$.
- $\hat{\mu}_{a,T} := \frac{1}{\sum_{t=1}^T 1[A_t = a]} \sum_{t=1}^T 1[A_t = a] Y_t$ is the sample mean.

✓ Remark: How to select candidates $\hat{\mathcal{S}}$?

Let $v_{a,qT} := \sqrt{\frac{\log(T)}{T}} \hat{\sigma}_{a,rT}$, and $\hat{a}_{rT} = \arg \max_{a \in [K]} \hat{\mu}_{a,rT}$.
Construct lower and upper confidence bounds as $\hat{\mu}_{a,rT} - v_{a,qT}$ and $\hat{\mu}_{a,rT} + v_{a,qT}$.
Define $\hat{\mathcal{S}}$ as $\hat{\mathcal{S}} := \{a \in [K] : \hat{\mu}_{a,rT} + v_{a,qT} \geq \hat{\mu}_{\hat{a}_{rT},rT} - v_{\hat{a}_{rT},rT}\}$.

Minimax and Bayes Optimality

- For the TS-EBA strategy, we prove the minimax and Bayes optimality.

- Let $\mathcal{E}$ be a set of consistent strategies. For any $\delta \in \mathcal{E}$, it holds that

$$\mathbb{P}_{\mu}(\hat{a}_T^{\delta} \neq a_{\mu}^*) \rightarrow 0.$$

Minimax optimality.

$$\begin{aligned} & \lim_{T \rightarrow \infty} \sup_{\mu \in \mathbb{R}^K} \sqrt{T} \text{Regret}_{\mu}^{\delta^{\text{TS-EBA}}} \\ & \leq \max \left\{ \frac{1}{\sqrt{e}} \max_{a \neq b} (\sigma_a + \sigma_b), \frac{K-1}{K} \sqrt{\sum_{a \in [K]} \sigma_a^2 \log(K)} \right\} \\ & \leq \inf_{\delta \in \mathcal{E}} \lim_{T \rightarrow \infty} \sup_{\mu \in \mathbb{R}^K} \sqrt{T} \text{Regret}_{\mu}^{\delta}. \end{aligned}$$

Bayes optimality.

$$\begin{aligned} & \lim_{T \rightarrow \infty} T \int_{\mu \in \mathbb{R}^K} \text{Regret}_{\mu}^{\delta^{\text{TS-EBA}}} d\Pi(\mu) \\ & \leq 4 \sum_{a \in [K]} \int_{\mathbb{R}^{K-1}} \sigma_{\setminus\{a\}}^{2*} h_a(\mu_{\setminus\{a\}}^* | \mu_{\setminus\{a\}}) dH^{\setminus\{a\}}(\mu_{\setminus\{a\}}) \\ & \leq \inf_{\delta \in \mathcal{E}} \lim_{T \rightarrow \infty} T \int_{\mu \in \mathbb{R}^K} \text{Regret}_{\mu}^{\delta} d\Pi(\mu), \end{aligned}$$

- $\sigma_{\setminus\{a\}}^{2*} = \sigma_{b^*}^2$ and $\mu_{\setminus\{a\}}^* = \mu_{b^*}$, where b^* be $\arg \max_{c \in [K] \setminus \{a\}} \mu_c$.
- $\mu_{\setminus\{a\}}$ is a parameter vector which removes μ_a from μ . $H^{\setminus\{a\}}(\mu_{\setminus\{a\}})$ is a prior of $\mu_{\setminus\{a\}}$.

Regret Decomposition

- The simple regret can be written as $\text{Regret}_{\mu} = \mathbb{E}_{\mu} [Y_{a_{\mu}^*}] - \mathbb{E}_{\mu} [Y_{\hat{a}_T}] = \sum_{b \neq a_{\mu}^*} (\mu_{a_{\mu}^*} - \mu_b) \mathbb{P}_{\mu}(\hat{a}_T = b)$.
 - $\mathbb{P}_{\mu}(\hat{a}_T \neq a_{\mu}^*)$ roughly upper bounded by $\sum_{b \neq a_{\mu}^*} \exp(-C^* T (\mu_{a_{\mu}^*} - \mu_b)^2)$ for some constant $C^* > 0$.

Regret analysis: For simplicity, let $K = 2$. Define $\Delta_{\mu} = \mu_1 - \mu_2$.

- For some constant $C > 0$, $\text{Regret}_{\mu} = \Delta_{\mu} \mathbb{P}_{\mu}(\hat{a}_T \neq a_{\mu}^*)$ can be written as $\text{Regret}_{\mu} \approx \Delta_{\mu} \exp(-CT(\Delta_{\mu})^2)$

The dependency of Δ_{μ} on T affects the evaluation of the regret.

- Δ_{μ} converges to zero with an order slower than $1/\sqrt{T} \rightarrow$ For some increasing function g , $\text{Regret}_{\mu} \approx \exp(-g(T))$.
 - Δ_{μ} converges to zero with an order of $1/\sqrt{T} \rightarrow$ For some $C > 0$, $\text{Regret}_{\mu} \approx \frac{C}{\sqrt{T}}$.
 - Δ_{μ} converges to zero with an order faster than $1/\sqrt{T} \rightarrow \text{Regret}_{\mu} \approx o(1/\sqrt{T})$
- $\rightarrow$ In the worst case, $\text{Regret}_{\mu} \approx \frac{C}{\sqrt{T}}$, where $\Delta_{\mu} = O(1/\sqrt{T})$.